Band algorithms for matrix multiplication

In these algorithms, matrices are divided into continuous sequences of rows or columns (*bands*). In the simplest case, a band can be a separate row or column.

In the algorithms discussed below, each process is used to compute one row of the resulting matrix product AB. In this case, the process must have access to the corresponding row of matrix A and the entire matrix B. Since simultaneous storage of the entire matrix B in all processes of a parallel application requires excessive memory consumption, calculations are organized in such a way that at any given time the processes contain only part of the elements of matrix B (one column or one row), and access to the rest is provided using message passing.

When describing band algorithms, it is assumed that the number of processes N coincides with the order of the multiplied matrices A and B, and the matrices are square. In the case where the order of the matrices M is a multiple of the number of processes N, *it is sufficient to process bands* containing M / N rows or columns in each process.

Band algorithm 1 (horizontal bands)

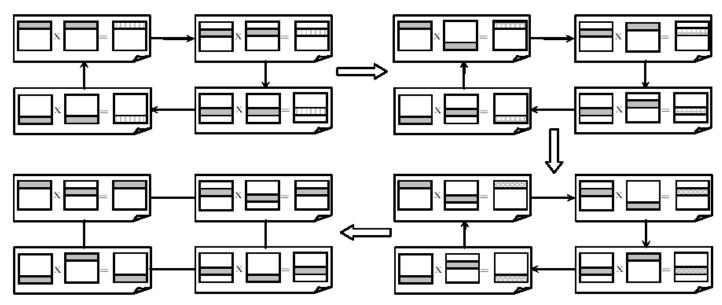
At the beginning, the elements of *the K*-th row of the matrix A and the elements of *the K*-th row of the matrix B are sent to the process of rank K. The elements of the row c, which will contain the result, i.e. the corresponding row of the product AB, are set to zero.

Then a loop is started (the number of iterations is N), during which two actions are performed:

- 1) A and matrix B with the same numbers are multiplied, and the results are added to the corresponding row element c;
- 2) the rows of matrix *B* are cyclically sent to neighboring processes (the direction of transfer can be arbitrary: either in increasing or decreasing ranks of processes).

After the loop completes, each process will contain the corresponding row of the product *AB*. All that remains is to send these rows to the master process.

The figure shows a diagram of algorithm 1, provided that cyclic transfer of rows of matrix B is performed in the direction of increasing process ranks (process of rank 0 sends its row to process of rank 1, process of rank 1 to process 2, etc.).



Band algorithm 2 (horizontal and vertical bands)

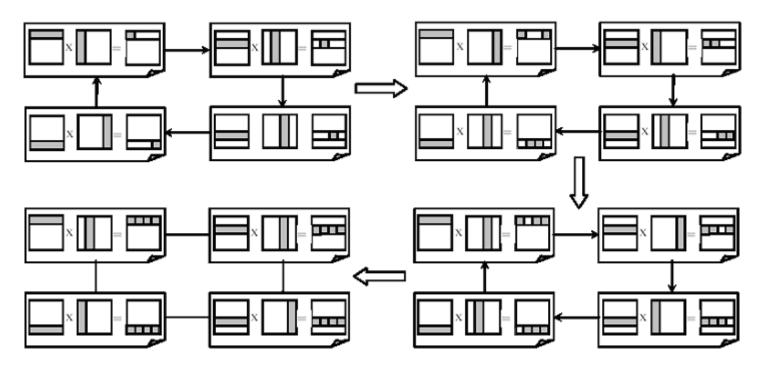
At the beginning, the elements of *the K*-th row of matrix *A* and the elements of *the K*-th column of matrix *B* are sent to the process of rank *K*.

Then a loop is started (the number of iterations is *N*), during which two actions are performed:

- 1) a multiplication of a row of matrix *A* and a column of matrix *B* contained in this process is performed, and the result is written to the corresponding element of row *c*;
- 2) the rows of matrix *B* are cyclically sent to neighboring processes (the direction of transfer can be arbitrary: either in increasing or decreasing ranks of processes).

After the loop completes, each process will contain a row c equal to one of the strings of the product AB. All that remains is to send the rows c to the master process.

The figure shows a diagram of algorithm 1, provided that cyclic forwarding of the columns of matrix B is performed in the direction of increasing process ranks (process of rank 0 sends its row to process of rank 1, process of rank 1 to process 2, etc.).



Block algorithms multiplication matrices

In these algorithms, matrices break up on blocks representing submatrices of the original matrices. For simplicity, we will assume that all matrices are square of size $N \times N$, and the number of blocks horizontally and vertically is the same and equal to q (the size of all blocks is equal to $K \times K$, where K = N / q). In this case, the matrix multiplication operation can be represented in block form:

$$\begin{pmatrix} A_{00}A_{01}\dots A_{0q-1} \\ \dots \\ A_{q-10}A_{q-11}\dots A_{q-1q-1} \end{pmatrix} \times \begin{pmatrix} B_{00}B_{01}\dots B_{0q-1} \\ \dots \\ B_{q-10}B_{q-11}\dots B_{q-1q-1} \end{pmatrix} = \begin{pmatrix} C_{00}C_{01}\dots C_{0q-1} \\ \dots \\ C_{q-10}C_{q-11}\dots C_{q-1q-1} \end{pmatrix}$$

In this case, each block C_{ij} of matrix C is defined as the product of the corresponding blocks of matrices A and B:

$$C_{ij} = \sum_{s=0}^{q-1} A_{is} B_{sj}$$

When partitioning data blockwise, it is natural to associate with each process the task of calculating one of the blocks of the resulting matrix C. In this case, the process must have access to all elements of the corresponding rows of matrix A and columns of matrix B. Since placing all the required data in each process will lead to their duplication and a significant increase in the amount of memory used, it is necessary to organize calculations in such a way that at each time the processes contain only one block of matrices A and B required for calculations, and access to the remaining blocks would be provided by message passing.

In these algorithms, it is convenient to introduce a two-dimensional Cartesian topology for processes by associating each process with its coordinates (i, j) in this topology (i, j = 0, ..., q - 1). It is assumed that the number of processes is equal to q^{2} .

Fox's block algorithm

Blocks A_{ij} , and B_{ij} of the original matrices are sent to the process with coordinates (i, j). In addition, the matrix C_{ij} , intended to store the corresponding block of the resulting product AB, is reset to zero.

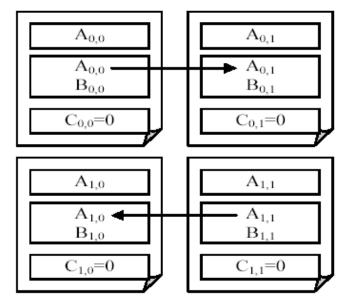
Then a loop is started in m (m = 0, ..., q - 1), during which three actions are performed:

- 1) for each row i (i = 0, ..., q 1), block A_{ij} of one of the processes is sent to all processes of the same row; in this case, the index j of the forwarded block is determined by the formula $j = (i + m) \mod q$;
- 2) the block of matrix A obtained as a result of such transfer and the block of matrix B contained in the process (i, j) are multiplied, and the result is added to the matrix C_{ij} :
- 3) for each column j (j = 0, ..., q 1), cyclic transfer of blocks of matrix B, contained in each process (i, j) of this column, is carried out in the direction of decreasing row numbers.

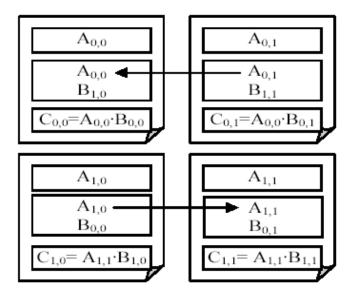
After completion of the loop, each process will contain a matrix C_{ij} equal to the corresponding block of the product *AB*. All that remains is to send these blocks to the master process.

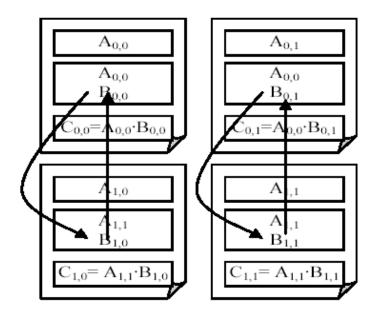
The figure shows a diagram of the Fox's algorithm in the case of q = 2.

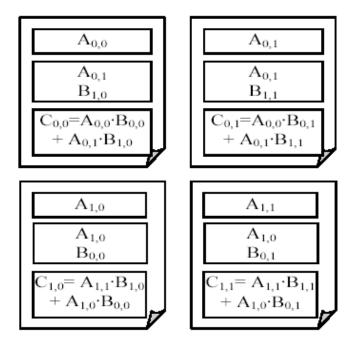
1 итерация



2 итерация





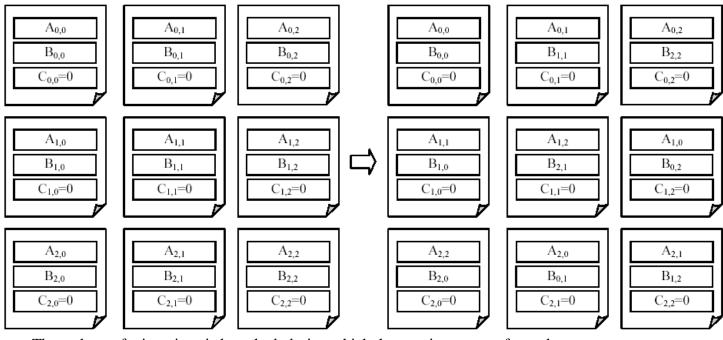


Cannon's block algorithm

Cannon's algorithm differs from Fox's algorithm in two ways. First, the initial transfer of blocks of matrices A and B to processes is performed in such a way that the resulting blocks can immediately be multiplied without any data transfers. Secondly, when organizing a loop, cyclic transfer is carried out not only of blocks of matrix B (by columns), but also by blocks of matrix A (by rows). Initial forwarding actions consist of the following steps:

- 1) blocks A_{ij} and B_{ij} are sent to each process (i, j), the matrix C_{ij} is reset to zero;
- 2) for each row i (i = 0, ..., q 1) of the Cartesian grid of processes, a cyclic shift of blocks of matrix A is performed by i positions to the left (i.e. in the direction of decreasing column numbers);
- 3) for each column j (j = 0, ..., q 1) of the Cartesian grid of processes, a cyclic shift of blocks of matrix B is performed by j positions upward (i.e. in the direction of decreasing row numbers).

The result of such a redistribution of blocks in case q = 2 is shown in the figure.



Then a loop of q iterations is launched, during which three actions are performed:

- 1) A and B contained in the process (i, j) are multiplied, and the result is added to the matrix C_{ij} ;
- 2) for each row i (i = 0, ..., q 1), cyclic transfer of blocks of matrix A, contained in each process (i, j) of this row, is performed in the direction of decreasing column numbers;
- 3) for each column j (j = 0, ..., q 1), cyclic transfer of blocks of matrix B, contained in each process (i, j) of this column, is performed in the direction of decreasing row numbers.

After completion of the loop, each process will contain a matrix C_{ij} equal to the corresponding block of the product *AB*. All that remains is to send these blocks to the master process.