

Algorithms and Data Structures

Module 1

Lecture 4

Graph traversals: depth-first search, breadth-first search and their applications. Part 2

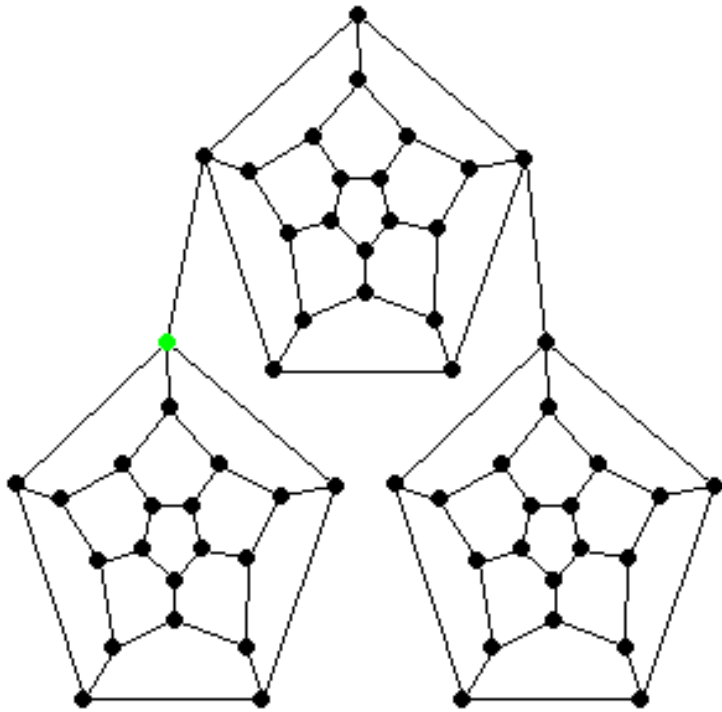
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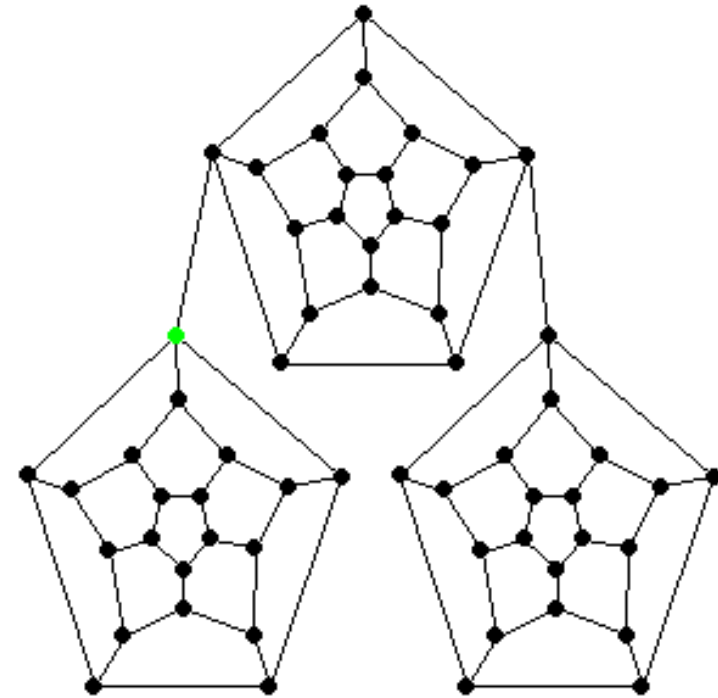
Graph traversals

Depth-First Search



www.combinatorica.com

Breadth-First Search

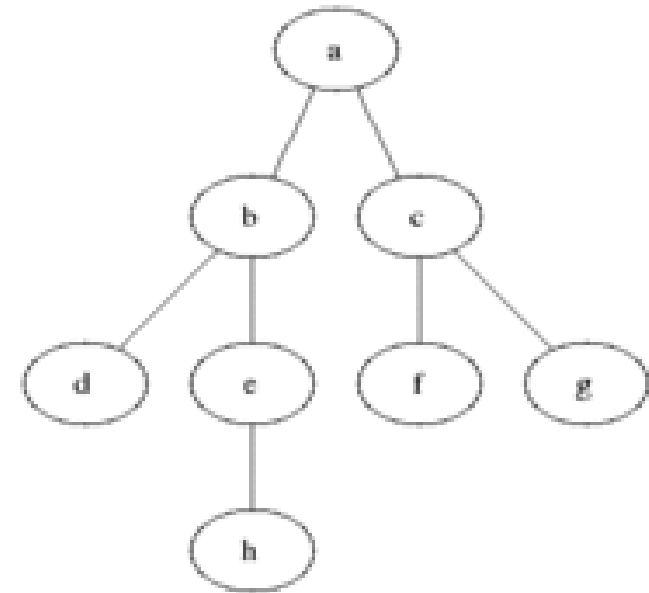


www.combinatorica.com

<https://www3.cs.stonybrook.edu/~skiena/combinatorica/animations/search.html>

BFS: Breadth-First Search

Visiting a vertex v ,
visit each of its unvisited neighbors,
then neighbors of the neighbors,
etc.

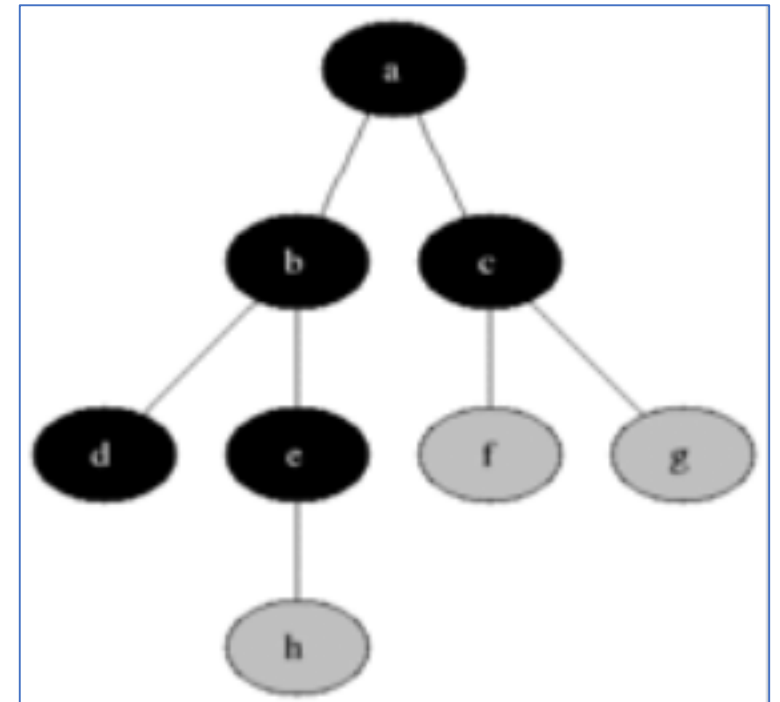


https://en.wikipedia.org/wiki/Breadth-first_search

BFS: Breadth-First Search

For keeping this order of visiting, we need to store neighbor vertices until we get them for processing.

We need a **queue**.



https://en.wikipedia.org/wiki/Breadth-first_search

Queue: abstract data structure

Queue = abstract data structure with two principal operations:

- Enqueue(*item*)
- Dequeue()



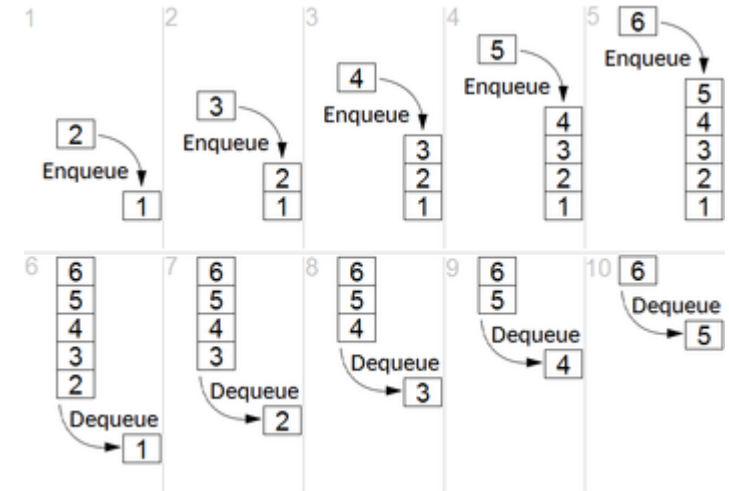
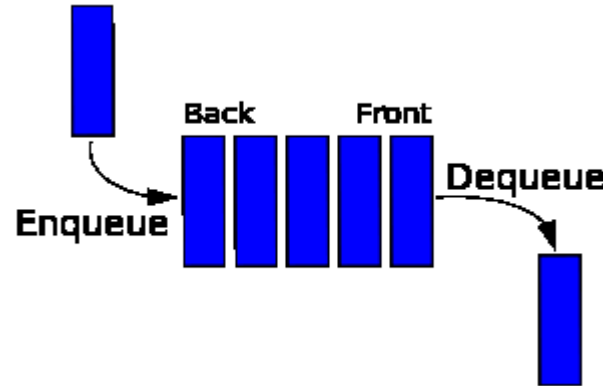
FIFO = First-In, First-Out

<https://www.javascripttutorial.net/javascript-queue/>

Queue: abstract data structure

Queue = abstract data structure with two principal operations:

- Enqueue(*item*)
- Dequeue()



FIFO = First-In, First-Out

[https://en.wikipedia.org/wiki/FIFO_\(computing_and_electronics\)](https://en.wikipedia.org/wiki/FIFO_(computing_and_electronics))

Queue: abstract data structure

```
// Abstract queue class
template <typename E> class Queue {
private:
    void operator =(const Queue&) {} // Protect assignment
    Queue(const Queue&) {} // Protect copy constructor

public:
    Queue() {} // Default
    virtual ~Queue() {} // Base destructor

    // Reinitialize the queue. The user is responsible for
    // reclaiming the storage used by the queue elements.
    virtual void clear() = 0;

    // Place an element at the rear of the queue.
    // it: The element being enqueued.
    virtual void enqueue(const E&) = 0;

    // Remove and return element at the front of the queue.
    // Return: The element at the front of the queue.
    virtual E dequeue() = 0;

    // Return: A copy of the front element.
    virtual const E& frontValue() const = 0;

    // Return: The number of elements in the queue.
    virtual int length() const = 0;
};
```

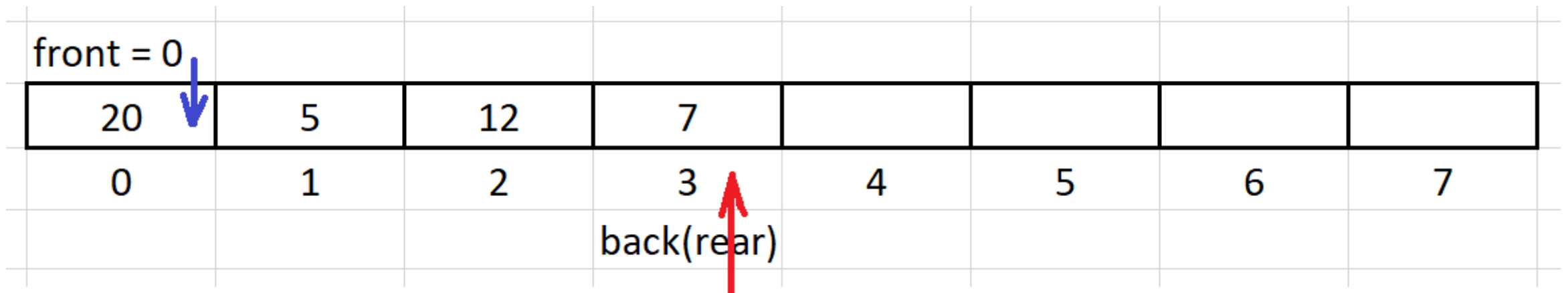
Queue: implementation

A queue data structure can be implemented in different ways:

- Array-based
 - linear array
 - circular array
- Linked-list based

Queue: array-based implementation

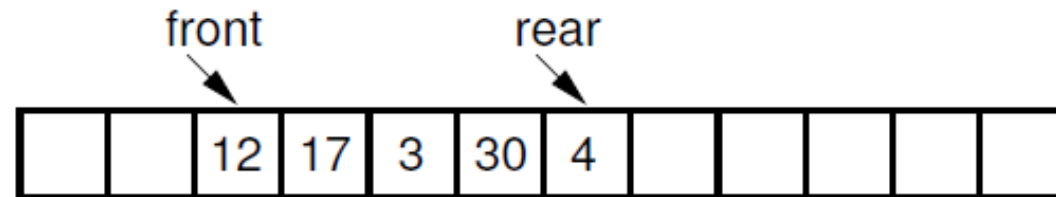
Array-based implementation: keep indices of the front and the back(rear) items of the queue.



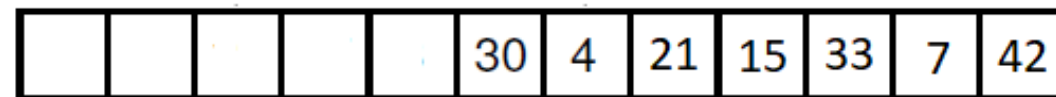
Queue: array-based implementation



(a)

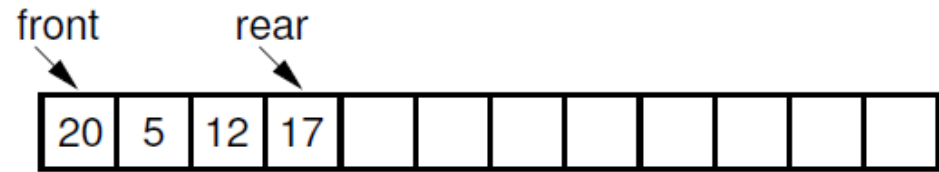


(b)

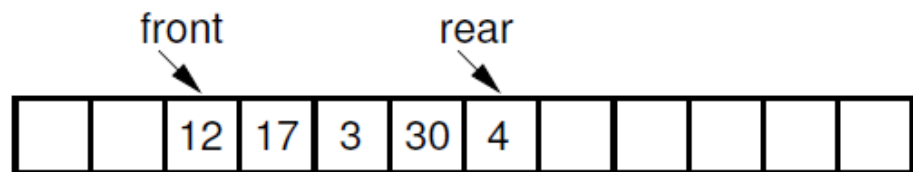


<https://people.cs.vt.edu/~shaffer/Book/>

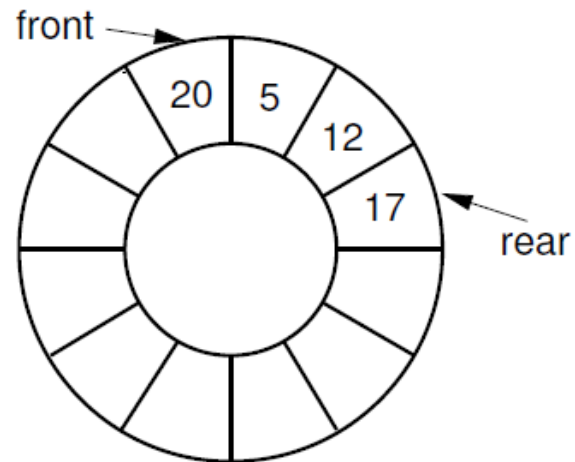
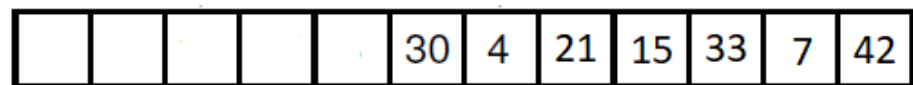
Queue: circular array-based implementation



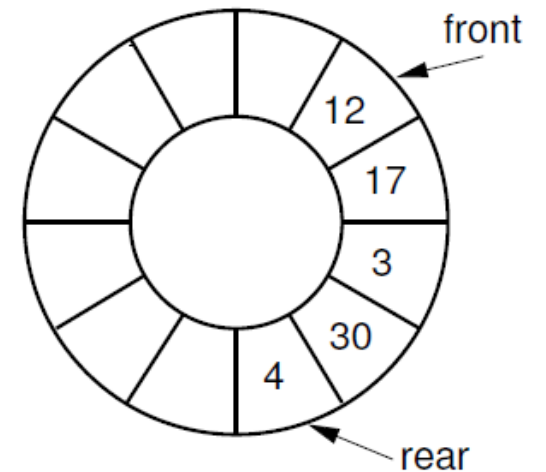
(a)



(b)



(a)



(b)

Queue: circular array-based implementation

Circular arrays implementation

We use an ordinary *linear* array (E^* or `std::vector<E>`) and apply modular arithmetic when we increment / decrement indices.

Mathematical operation **mod**: $12 \bmod 10 = 2$; $99 \bmod 10 = 9$.

For an integer x and positive integer m , **$x \bmod m$** is an integer $y \in \{0, \dots, m - 1\}$ such that $x = y + km$ for some integer k .

In C++ we use **%** operation.

Queue: circular array-based implementation

Circular arrays implementation

```
void enqueue(const E& it) { // Put "it" in queue
    Assert(((rear+2) % maxSize) != front, "Queue is full");
    rear = (rear+1) % maxSize; // Circular increment
    listArray[rear] = it;
}

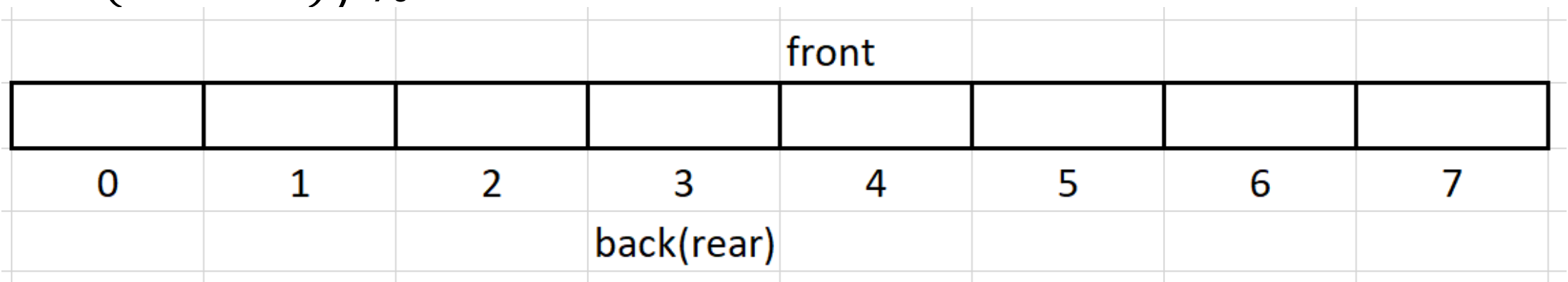
E dequeue() { // Take element out
    Assert(length() != 0, "Queue is empty");
    E it = listArray[front];
    front = (front+1) % maxSize; // Circular increment
    return it;
}
```

<https://people.cs.vt.edu/~shaffer/Book/>

Queue: circular array-based implementation

There is a potential problem with this implementation. Lets look at two cases:

- a) Empty queue \Rightarrow the 'back' index is just before the 'front' index \Rightarrow $back = front - 1$.
- b) Full queue $\Rightarrow back = front + (size - 1) \Rightarrow back = (front + (size - 1)) \% size \Rightarrow back = front - 1$.



Queue: circular array-based implementation

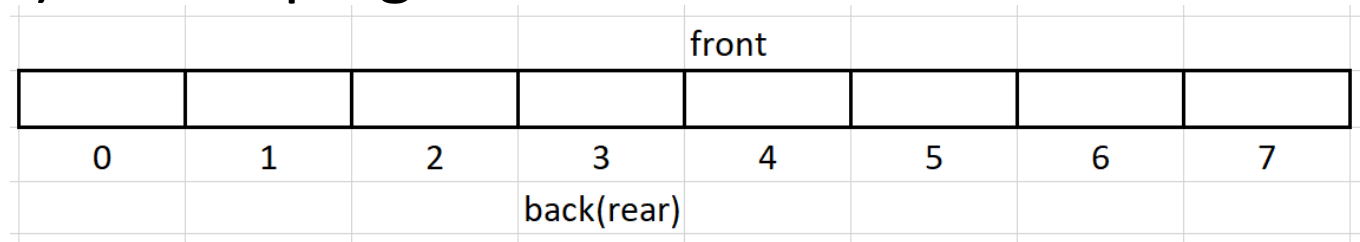
Two possible solutions:

1) Keep an explicit count of the items in the queue:

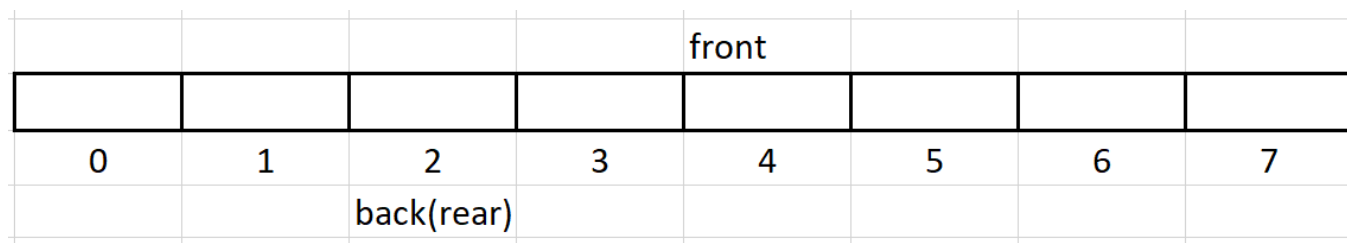
- Count = 0 => empty queue
- Count = Size => full queue

2) Use array of size $(n+1)$ for keeping maximum n items:

• Empty queue:



• Full queue:



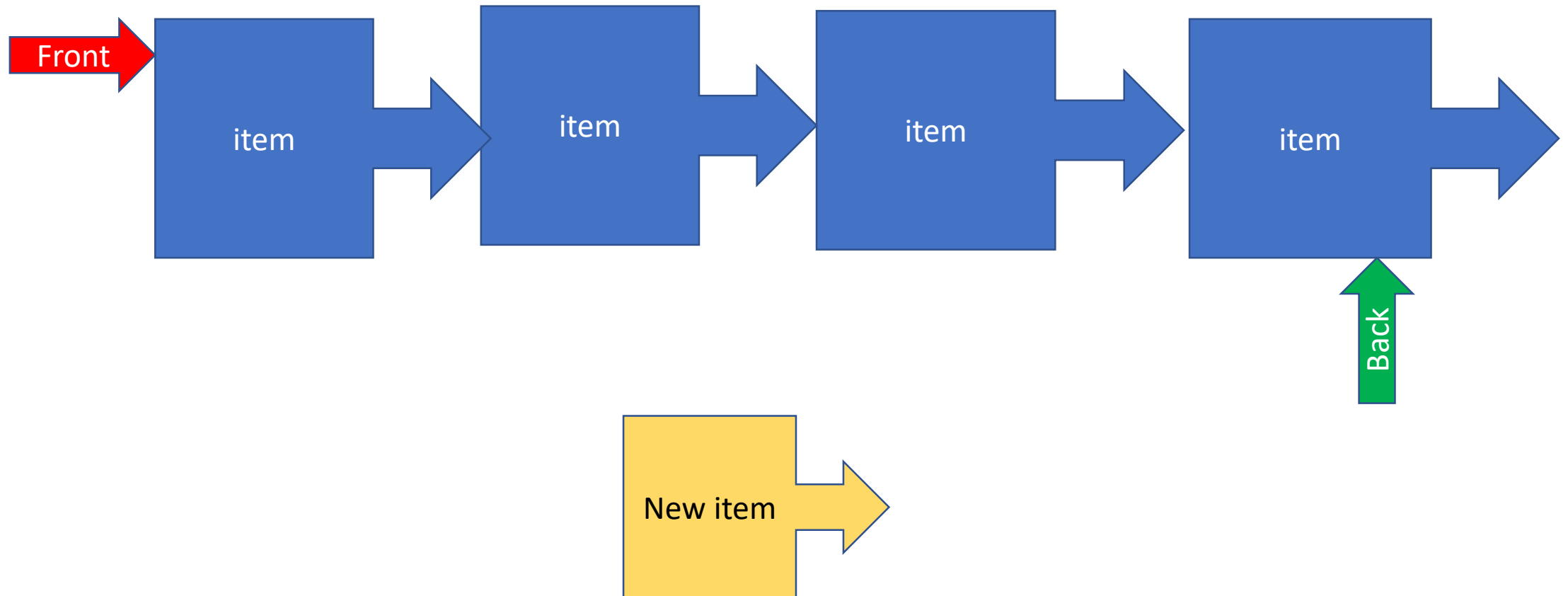
Queue: circular array-based implementation

```
array<T> a;  
int j;  
int n;  
  
bool add(T x) {  
    if (n + 1 > a.length) resize();  
    a[(j+n) % a.length] = x;  
    n++;  
    return true;  
}  
  
T remove() {  
    T x = a[j];  
    j = (j + 1) % a.length;  
    n--;  
    if (a.length >= 3*n) resize();  
    return x;  
}  
  
void resize() {  
    array<T> b(max(1, 2*n));  
    for (int k = 0; k < n; k++)  
        b[k] = a[(j+k)%a.length];  
    a = b;  
    j = 0;  
}
```

```
// Array-based queue implementation  
template <typename E> class AQueue: public Queue<E> {  
private:  
    int maxSize;           // Maximum size of queue  
    int front;            // Index of front element  
    int rear;             // Index of rear element  
    E *listArray;         // Array holding queue elements  
  
public:  
    AQueue(int size = defaultSize) { // Constructor  
        // Make list array one position larger for empty slot  
        maxSize = size+1;  
        rear = 0; front = 1;  
        listArray = new E[maxSize];  
    }  
  
    ~AQueue() { delete [] listArray; } // Destructor  
  
    void clear() { rear = 0; front = 1; } // Reinitialize  
  
    void enqueue(const E& it) { // Put "it" in queue  
        Assert(((rear+2) % maxSize) != front, "Queue is full");  
        rear = (rear+1) % maxSize; // Circular increment  
        listArray[rear] = it;  
    }  
  
    E dequeue() { // Take element out  
        Assert(length() != 0, "Queue is empty");  
        E it = listArray[front];  
        front = (front+1) % maxSize; // Circular increment  
        return it;  
    }  
  
    const E& frontValue() const { // Get front value  
        Assert(length() != 0, "Queue is empty");  
        return listArray[front];  
    }  
  
    virtual int length() const // Return length  
    { return ((rear+maxSize) - front + 1) % maxSize; }  
};
```


Queue: dynamic list-based implementation

A dynamic list data structure with 'front' and 'back' pointers.



BFS: queue-based implementation

BFS (G)

Select $s \in V$

Enqueue(s)

While (Queue is not empty):

$v = \text{Dequeue}()$

 if v is unvisited:

 Mark v as 'visited'

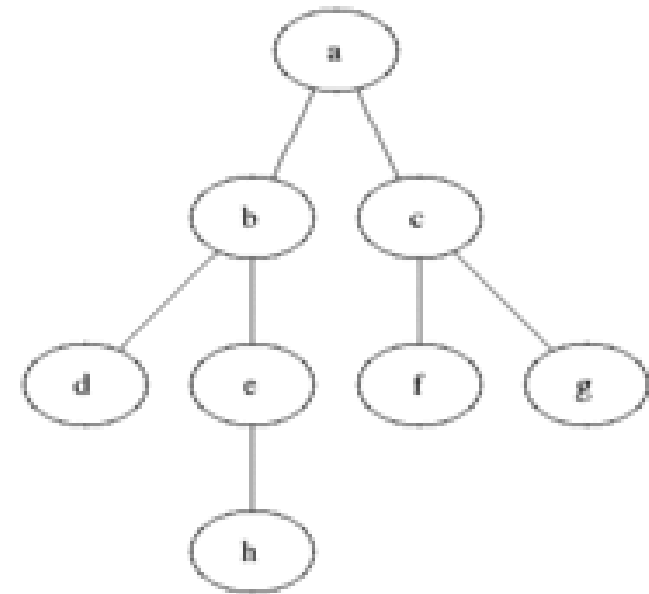
 For each u in $\text{Adj}(v)$:

 Enqueue(u)

BFS: applications

- 1) Detecting connected components.
- 2) Calculating distances.

Principal idea: visiting a vertex v , visit each of its unvisited neighbors, then neighbors of the neighbors, etc.



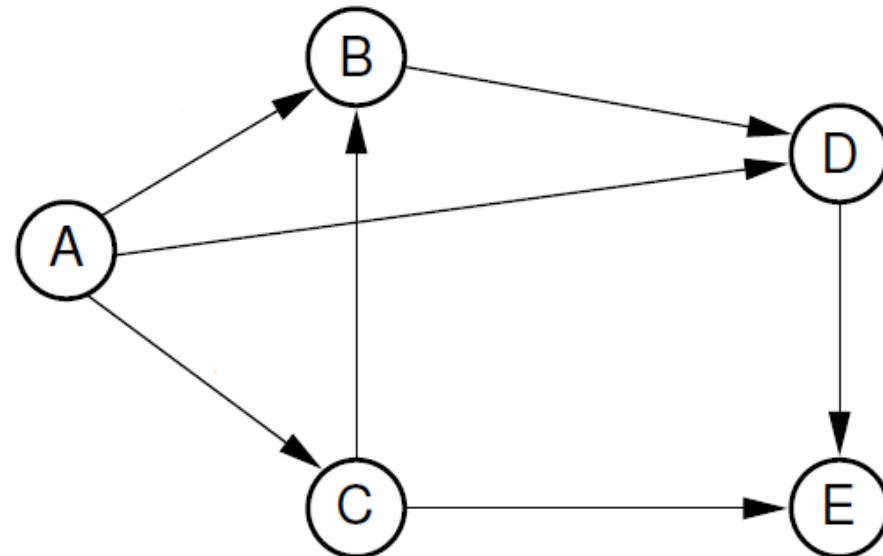
https://en.wikipedia.org/wiki/Breadth-first_search

BFS: applications

Graph $G=(V,E)$.

A *distance* between vertices u and v is the minimum length of the path between u and v .

$\text{dist}(A,E) = 2$

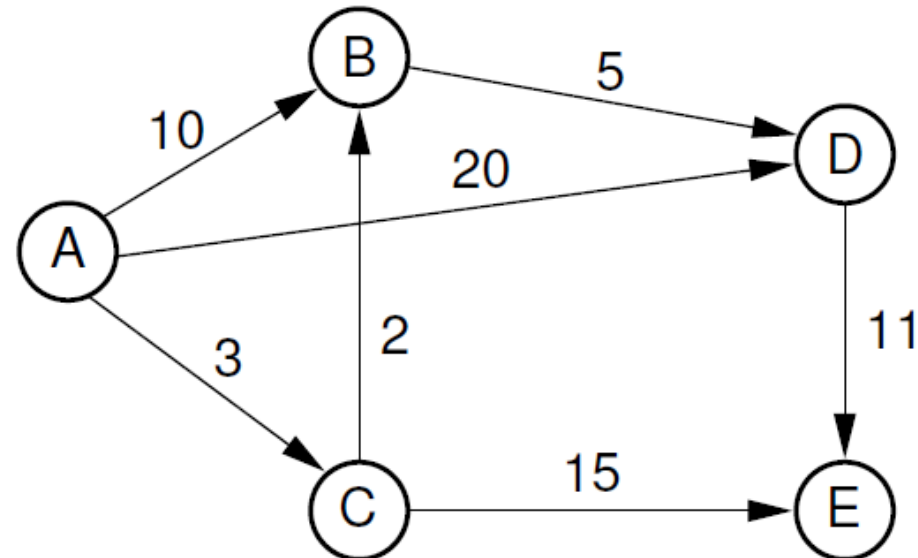


BFS: applications

Weighted graph $G=(V,E)$, $w: E \rightarrow R$

A *distance* between vertices u and v is the minimum weight (=sum of edges' weights) of the path between u and v .

$\text{dist}(A,E) = 18$



BFS: applications

For unweighted graphs distances from $s \in V$ to all other vertices can be calculated using BFS.

For weighted graphs: Dijkstra algorithm works like a BFS and calculates distances (from $s \in V$ to all other vertices) on a graph.